# Dr Chris Gaskett

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I'm an experienced software developer and researcher. My background includes technical lead and senior software engineer roles; leading R&D as an active developer; university lecturing in software; and industrial research in Japan. I have published papers across specialties including machine learning, machine vision, and robotics. I've recently worked on applied cryptography and use of a distributed NoSQL DBMS. I'm available for onsite, hybrid and remote positions.

#### **SKILLS SUMMARY**

- Current software development in Java (Spring) with earlier work in many other languages
- Cryptography (including post-quantum), machine learning, image processing, robotics
- Research skills including discovering and comparing prior work, developing novel solutions, experimental design, statistical analysis, reporting results.
- Project management including including agile/iterative approaches (certified project manager)
- Communication skills including writing for various audiences, public speaking, discussing technical issues with lay-people, and media liaison
- Teaching, including curriculum development, coordinating delivery of subjects.

#### PROFESSIONAL EMPLOYMENT

# Head of Research and Development, CoolRock Software, Melbourne Australia

April 2007-Mar 2022

(Previously Technical Lead, Senior Software Engineer)

- Research and development on cryptography (including post-quantum). FIPS compliance.
- High speed indexing and search using a distributed NoSQL DBMS. AWS/Azure deployment
- Extensive Java (Spring Boot) development with earlier work in c++, c#, and ANTLR
- Mobile App development in c#
- Project management and service management for internal and customer deployment projects from startup company to enterprise product vendor

# Lecturer (permanent), School of Maths, Physics and Information Technology, James Cook University, Cairns, Australia Feb 2004-Mar 2007

- Lecturing in project management, c++, unix, and database systems
- Development and coordination for project management subjects. Developed an industry projects scheme for students and received a national award (Carrick Citation) for outstanding contributions to student learning.
- Managed project subject delivery across Cairns, Townsville, Sydney, and Singapore campuses

- Coordinated student supervision by lecturers in Cairns to support student projects
- Carried out on-site review of School of IT organisation and lecturing at the Singapore campus

# Research Engineer, Department of Humanoid Robotics and Computational Neuroscience, Advanced Telecommunications Research Institute International (ATR International), Kyoto, Japan Jul 2002-Feb 2004

- Research on reaching strategies for a humanoid robot with active stereo vision
- Distributed system development in C++ and Scheme under MS Windows and VxWorks (real-time OS), learning system implementation.

## Associate Researcher, Active Safety Laboratory,

### Toyota Central Research and Development Laboratories, Nagoya, Japan Jul 2001-Jun 2002

- Research on identifying road regions through stereo vision
- Post processing of human gaze direction data from seeingmachines FaceLAB

Other experience: Retail, CFA volunteer, parkrun volunteer, AEC polling official.

#### **EDUCATION**

### PhD in Systems Engineering, "Q-Learning for Robot Control"

1998-2002

Supervisor: Professor Alexander Zelinsky,

Systems Engineering, The Australian National University (ANU), Canberra

Development of a control system for using reinforcement learning

Electronics design for the Kambara autonomous underwater vehicle

Development in Java, C++ under MS Windows, Unix, VxWorks

#### **Bachelor Degree in Computer Systems Engineering**

1993-1997

with first-class honours, Royal Melbourne Institute of Technology University (RMITU)

Fault trees and FMEA for fault finding (VDO instruments)

# **Bachelor Degree in Computer Science**

1993–1997

with distinction, RMITU, Melbourne

Speaker independent speech recognition using neural networks

Awards: Kernot Medal: RMITU engineering faculty award for best final year engineering student, across all disciplines at RMITU, Double Degree Fifth Year Prize, ENGenius Display Award, RS Components Award, KRONE Australia Prize.

#### **SELECTED PUBLICATIONS**

- Hand-Eye Coordination through Endpoint Closed-Loop and Learned Endpoint Open-Loop Visual Servo Control, Chris Gaskett, Ales Ude, and Gordon Cheng, The International Journal of Humanoid Robotics, Vol 2, No 2, 2005 pp. 203-224
- Online Learning of a Motor Map for Humanoid Robot Reaching, Chris Gaskett and Gordon Cheng, Proceedings of the 2nd International Conference on Computational Intelligence, Robotics and Autonomous Systems (CIRAS 2003), (Singapore, December 2003)

- Reinforcement Learning Under Circumstances Beyond its Control, Chris Gaskett, Proceedings of the International Conference on Computational Intelligence for Modelling Control and Automation (CIMCA2003), (Vienna, Austria, February 2003)
- Japanese Patent: 視線座標変換方法、それのプログラムおよびそれを記録した記録媒体 (Gaze coordinate transformation method) by Chris Gaskett, 2002.
- **Q-Learning for Robot Control**, Chris Gaskett, PhD thesis from the Robotic Systems Laboratory, part of the Research School of Information Sciences and Engineering at the Australian National University.
- Learning Implicit Models during Target Pursuit, Chris Gaskett, Peter Brown, Gordon Cheng and Alex Zelinsky, *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA2003), (Taiwan, May 2003).*
- Reinforcement Learning for a Vision Based Mobile Robot, Chris Gaskett, Luke Fletcher, and Alex Zelinsky, Proceedings of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2000) (Takamatsu, Japan, October 2000).
- Q-Learning in Continuous State and Action Spaces, Chris Gaskett, David Wettergreen, and Alex Zelinsky, *Proceedings of the 12th Australian Joint Conference on Artificial Intelligence* © *Springer-Verlag (Sydney Australia, 1999)*.
- Reinforcement Learning applied to the control of an Autonomous Underwater Vehicle, Chris Gaskett, David Wettergreen, and Alex Zelinsky, *Proceedings of Australian Conference on Robotics and Automation (Brisbane, Australia, March 1999)*.